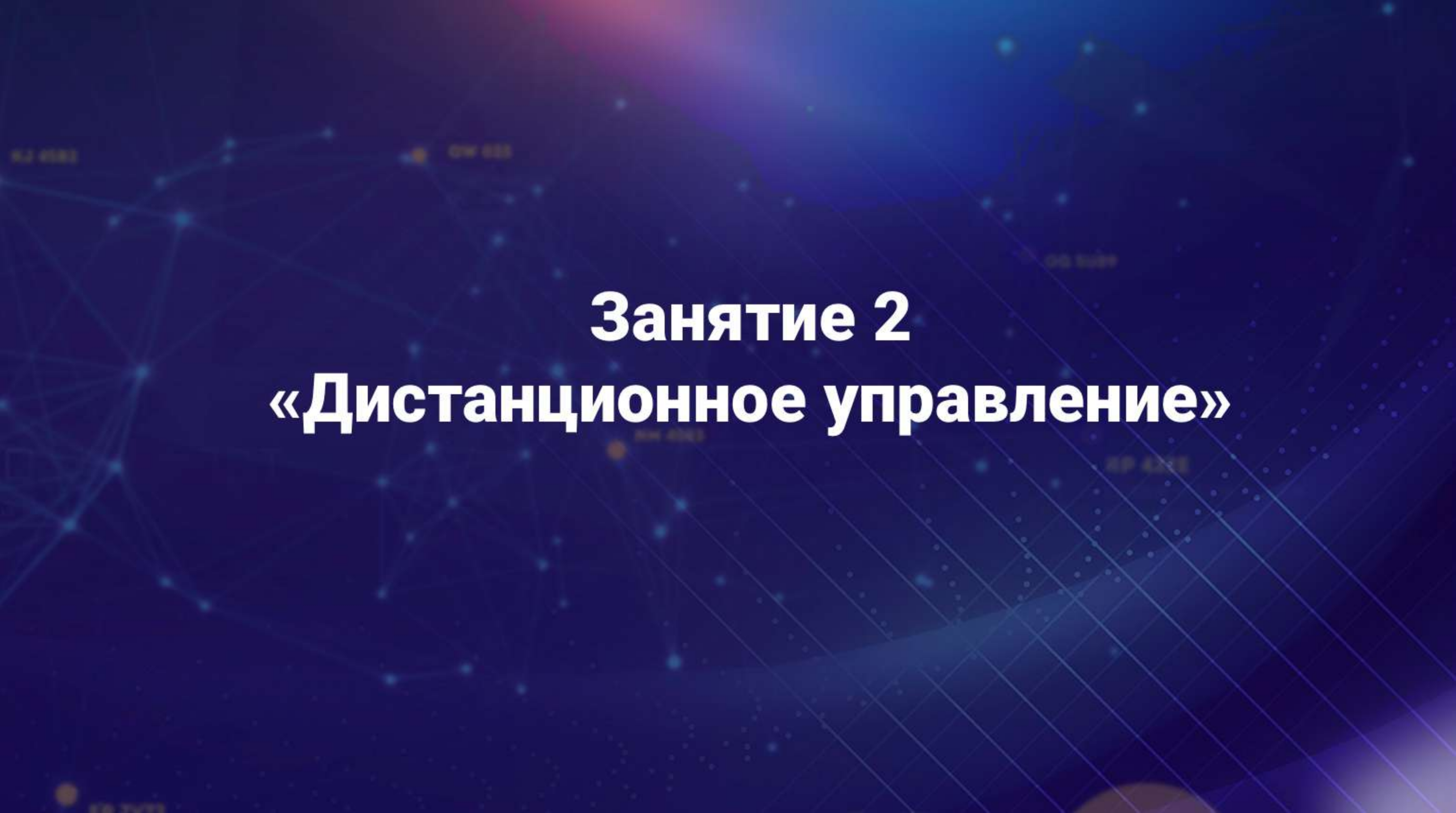




Занятие 2

«Дистанционное управление»

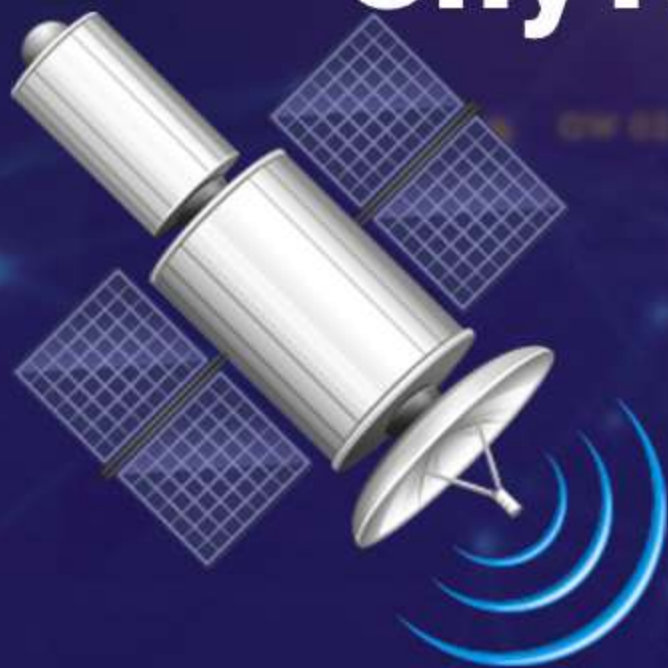
Технология Bluetooth



Технология Wi-Fi

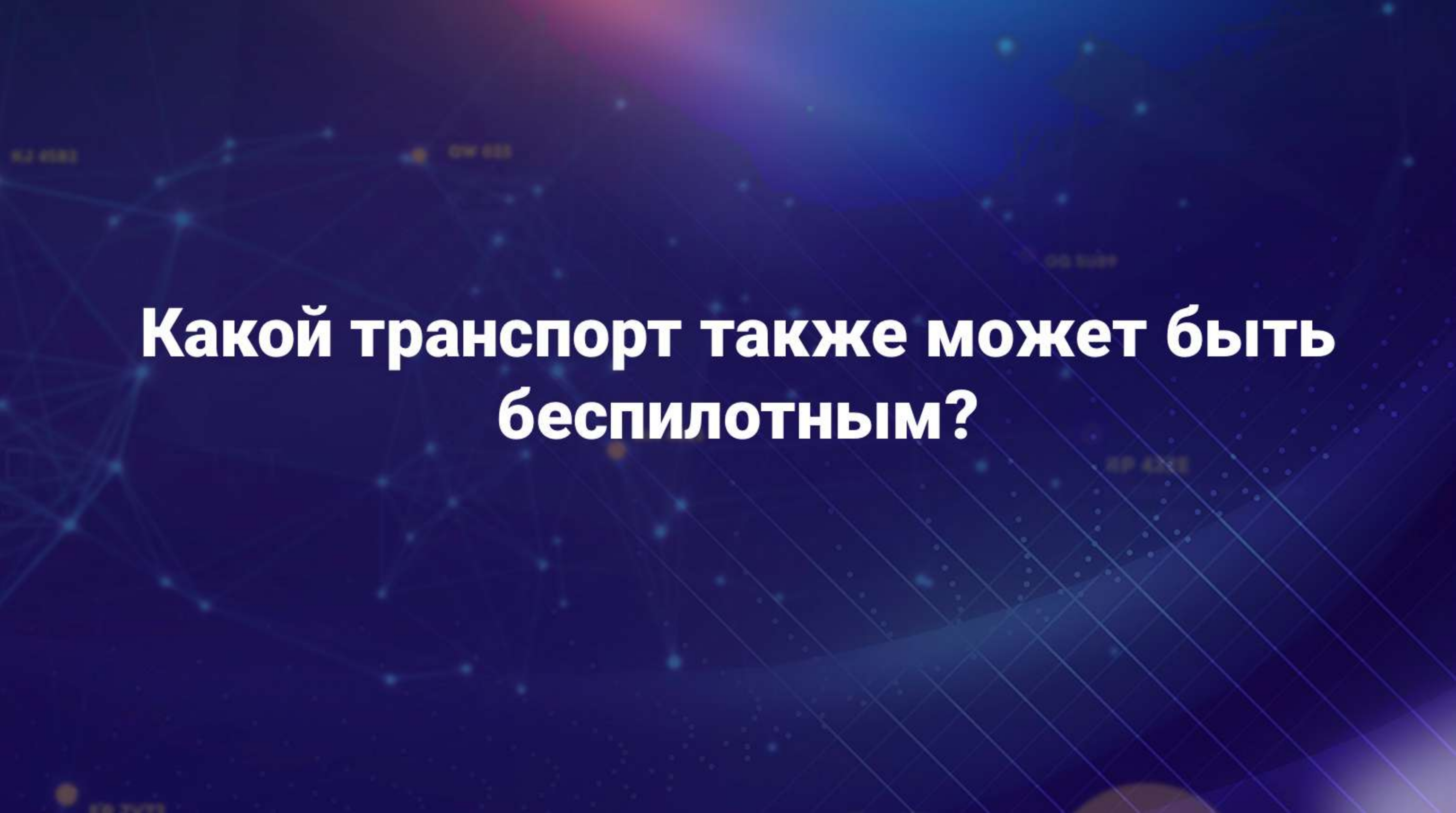


Спутниковое управление



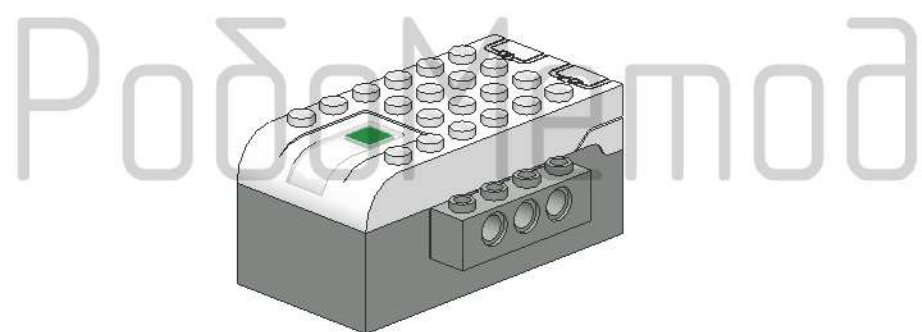
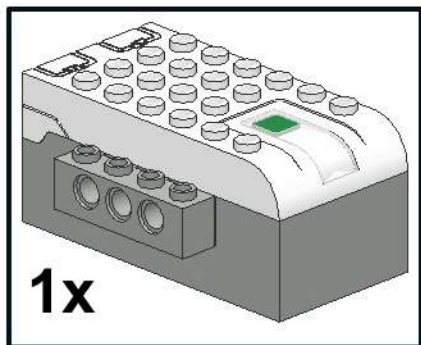
Радиоуправление



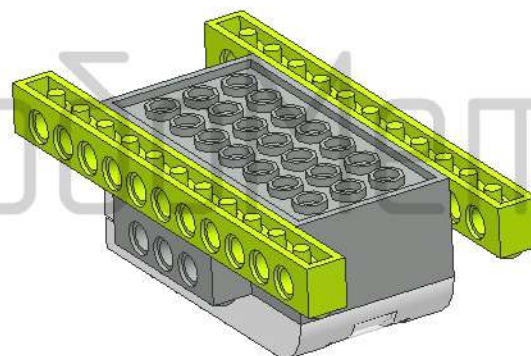
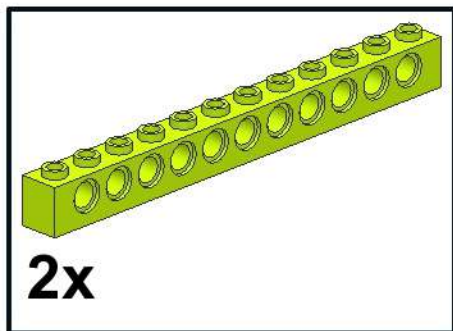


**Какой транспорт также может быть
беспилотным?**

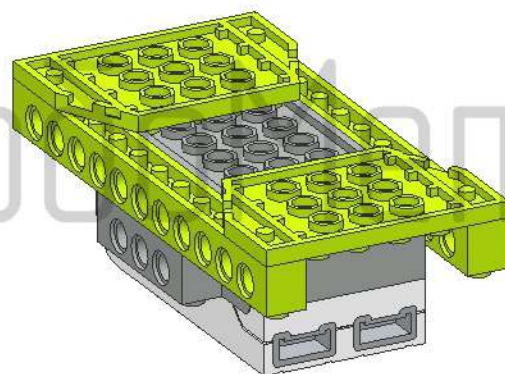
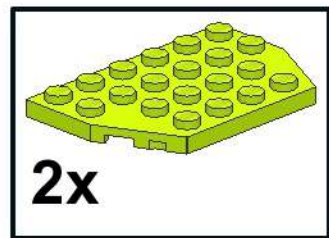
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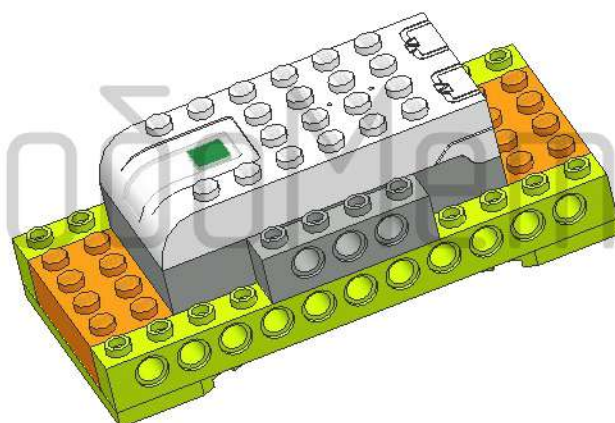
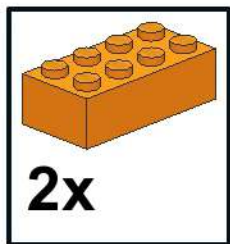
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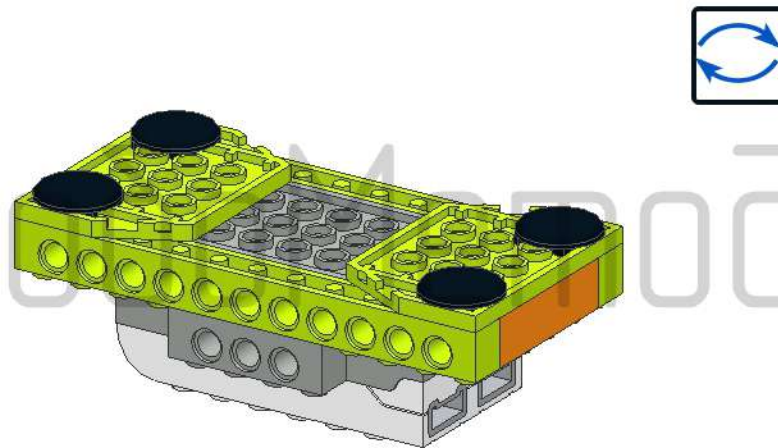
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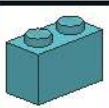
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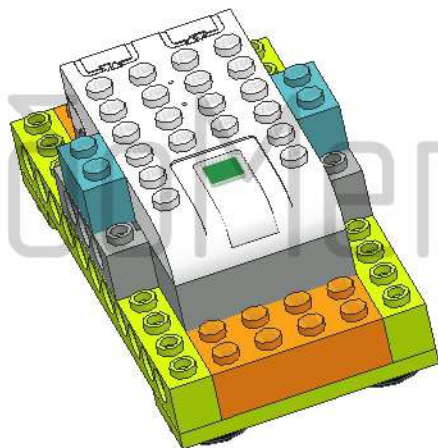
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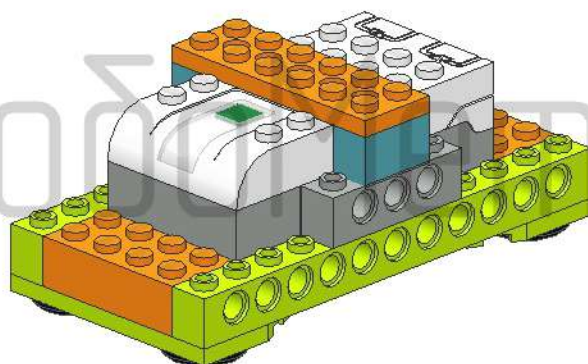
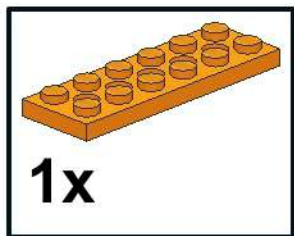
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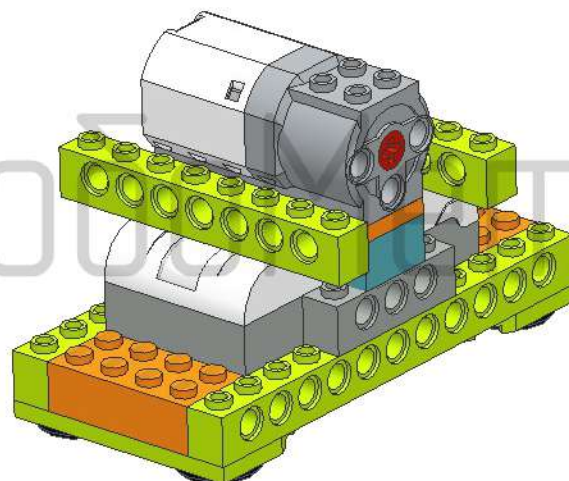
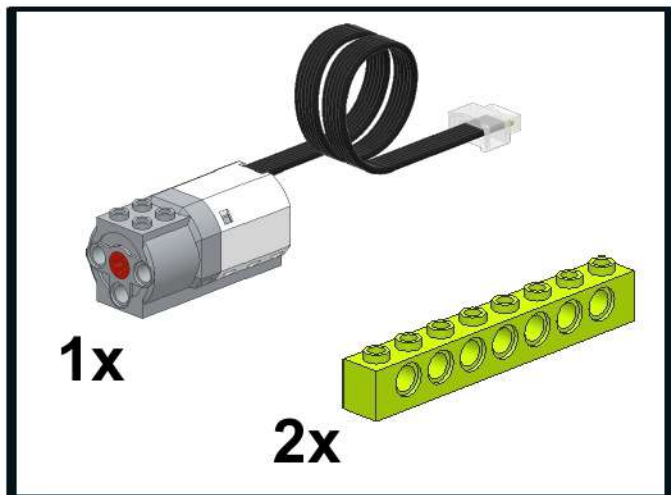
2x

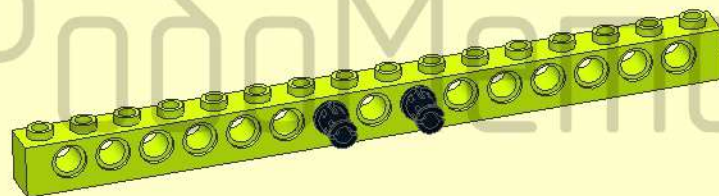
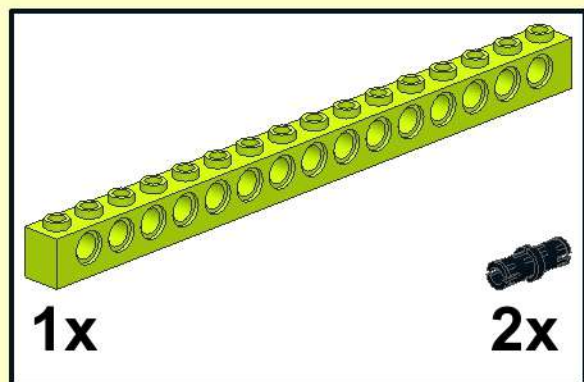


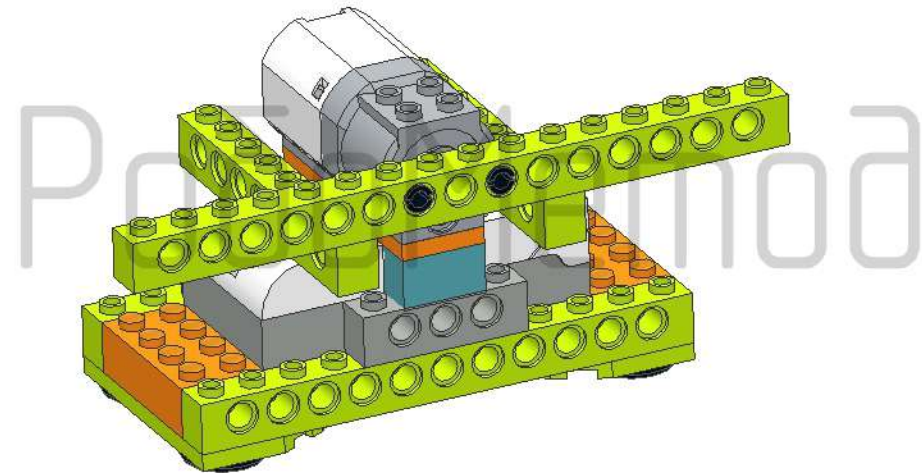
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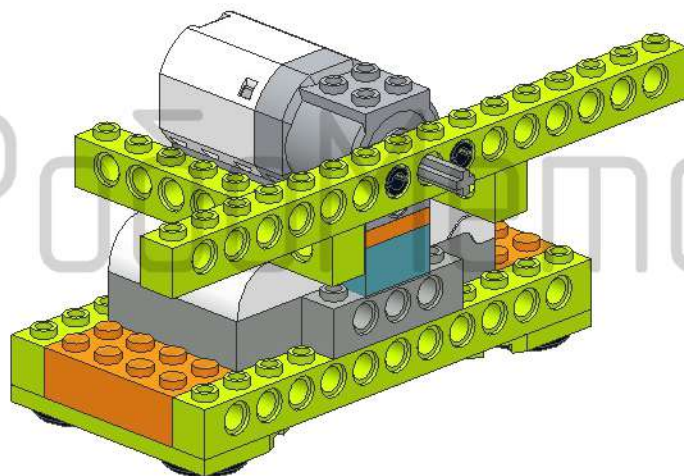
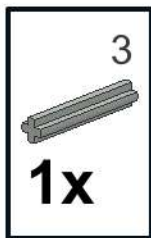
8







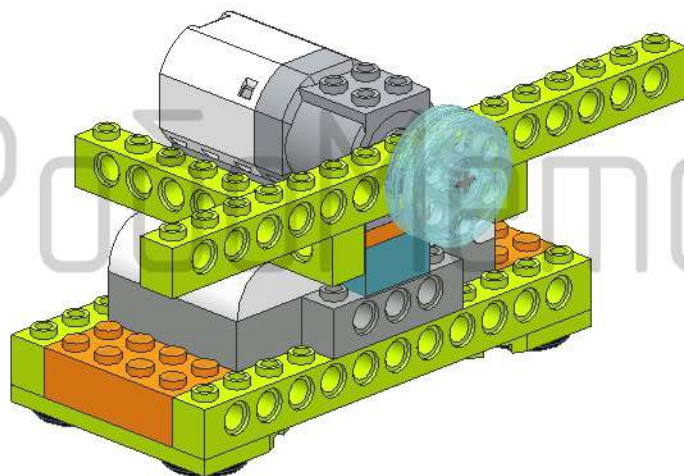
10



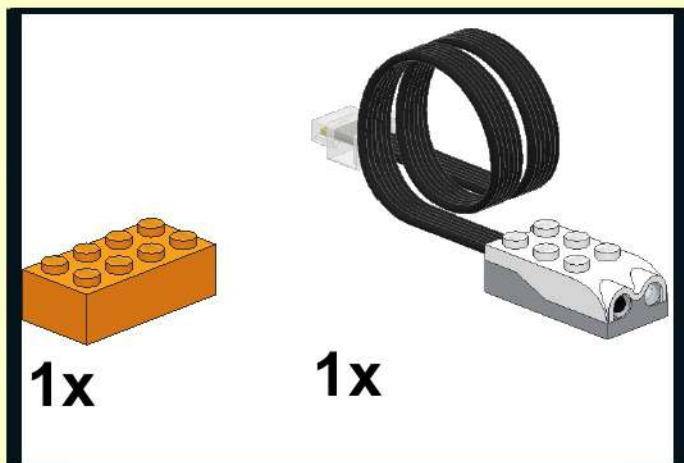
11



2x



1

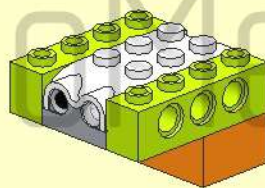
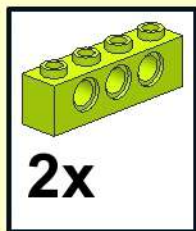


РодоМетод



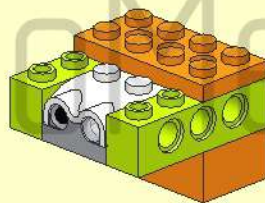
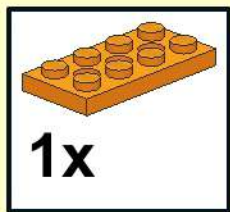
This image shows the assembly diagram for step 1. It depicts the 1x4 white Technic brick with the black cable attached, placed on top of the 1x4 orange Technic brick. The quantity '1x' is written below the assembly.

2

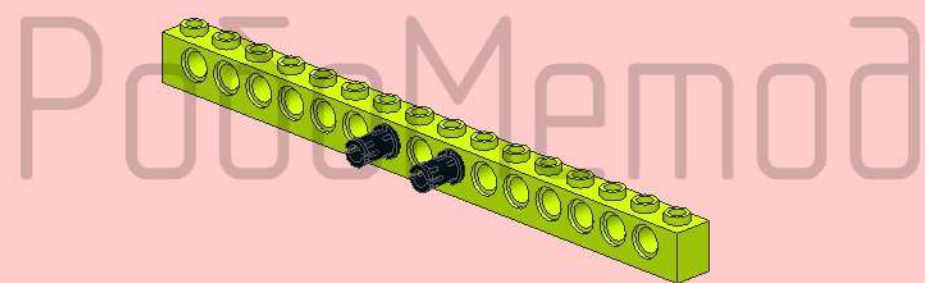
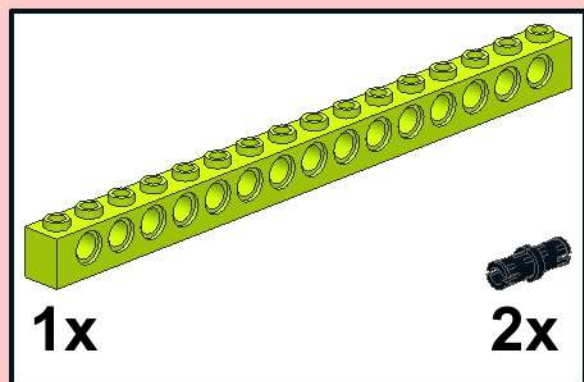


Роден Метод

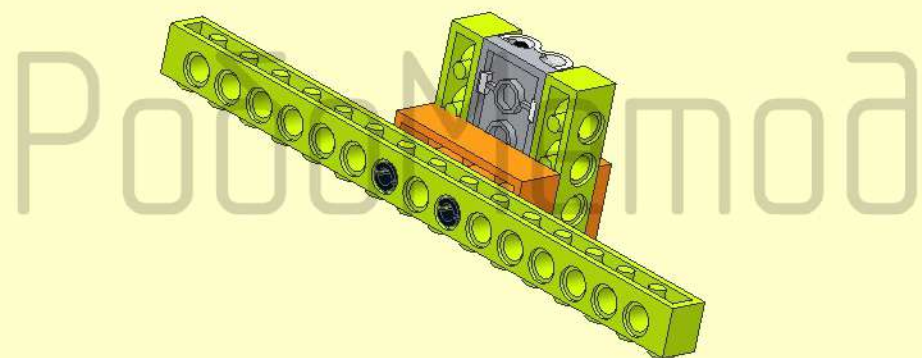
3



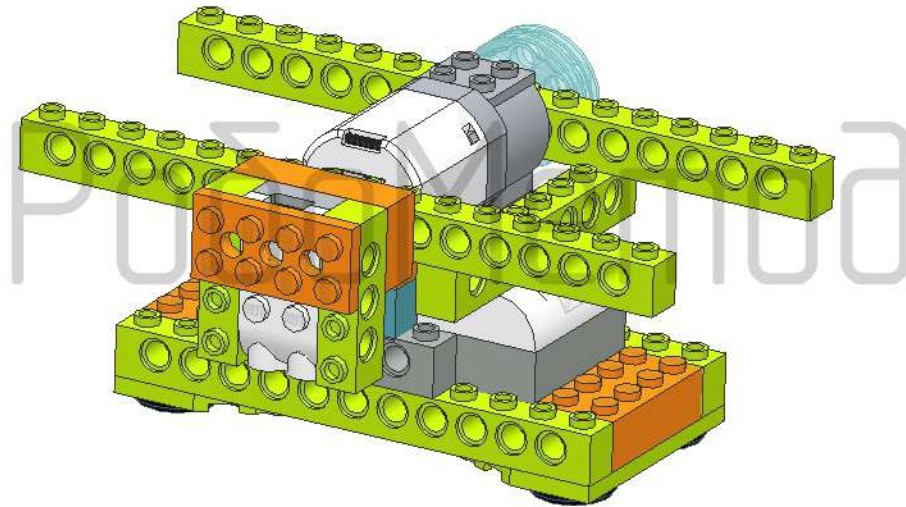
Роден Метод



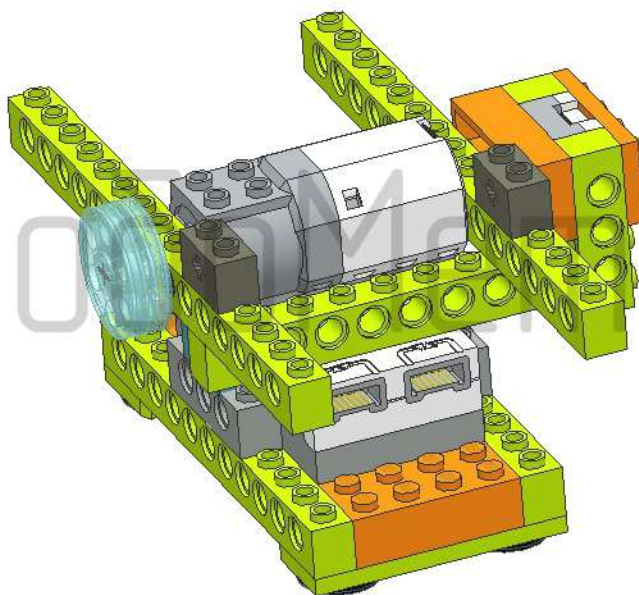
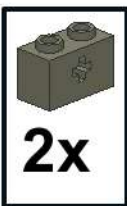
4



12

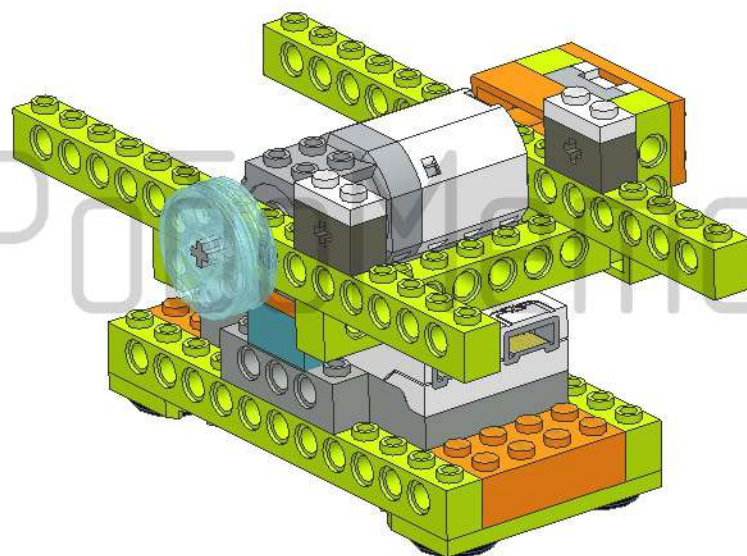


13

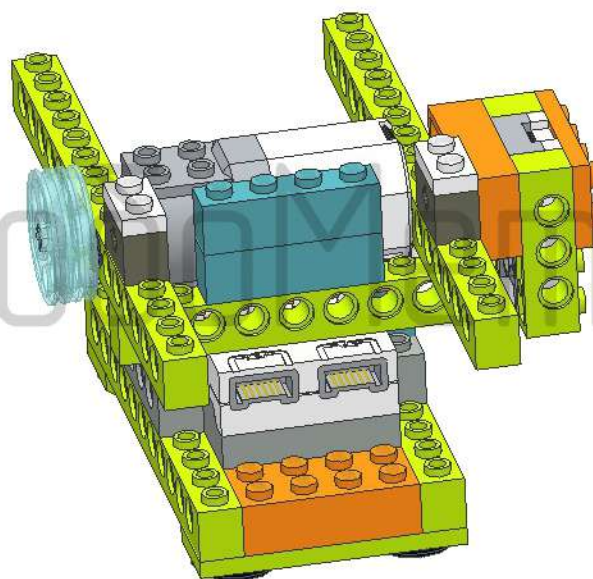
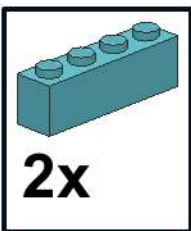




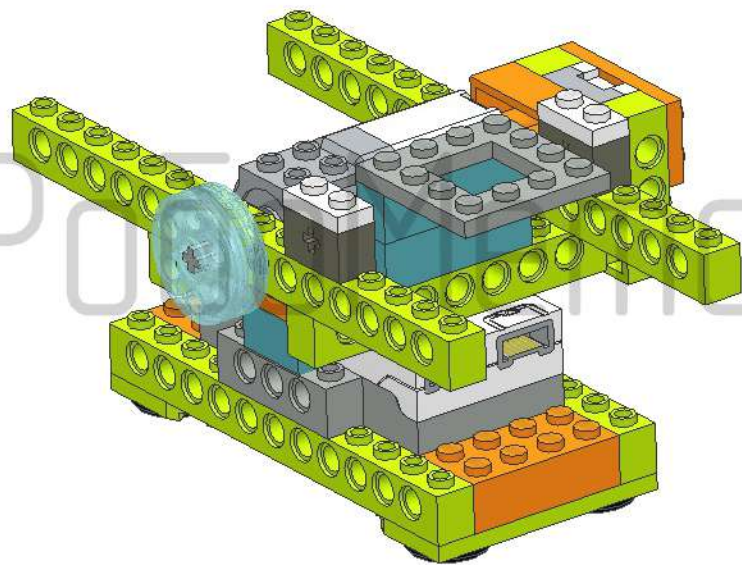
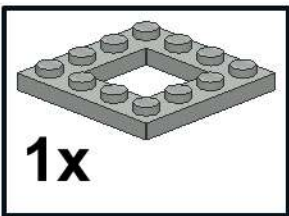
2x

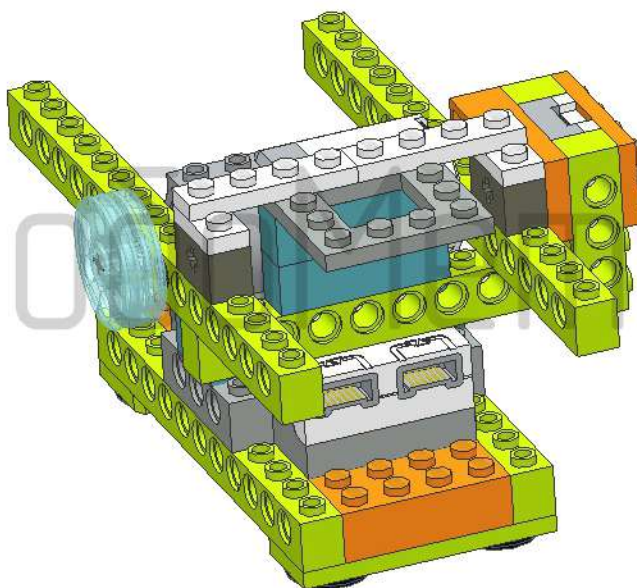


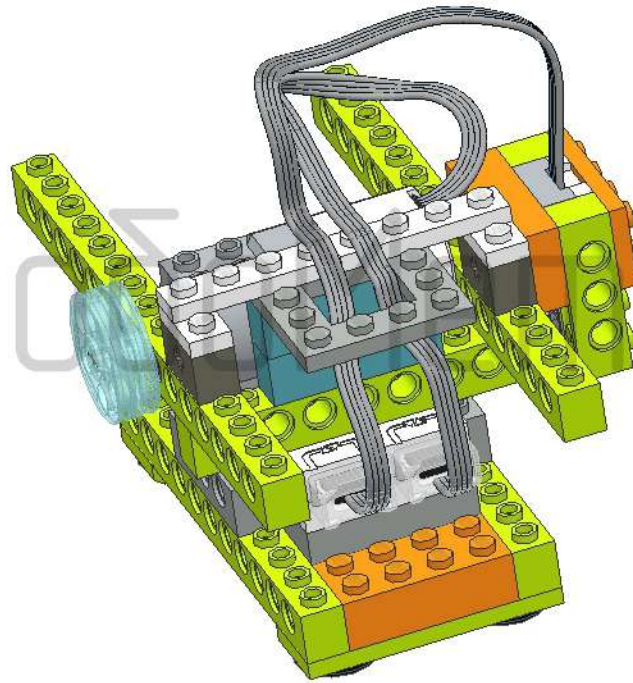
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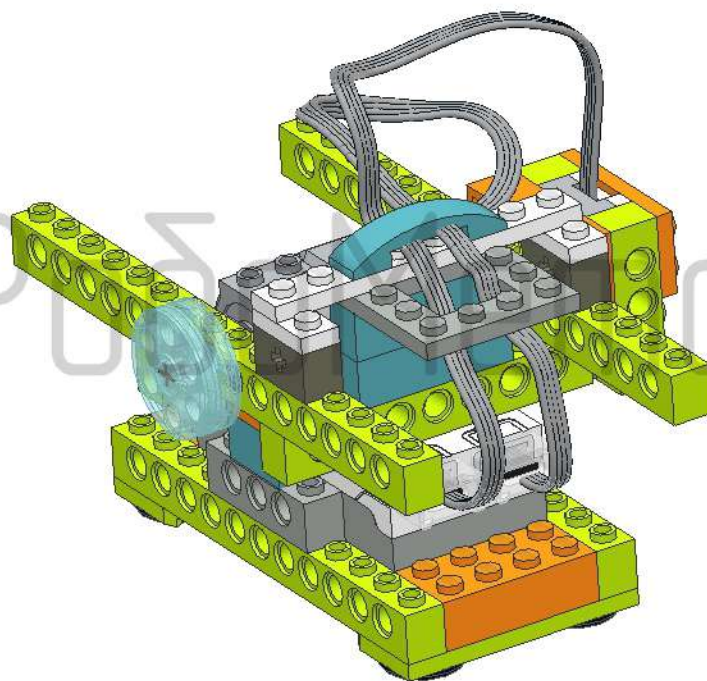
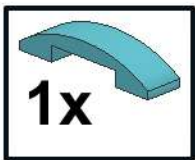
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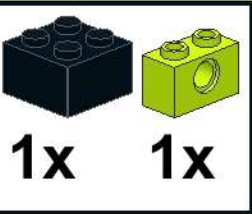




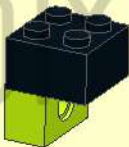


19

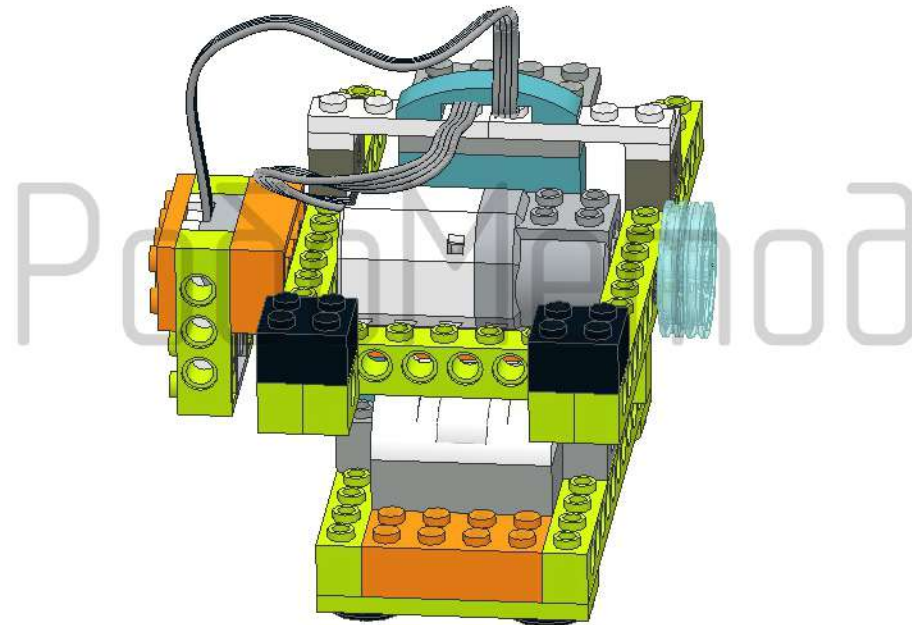




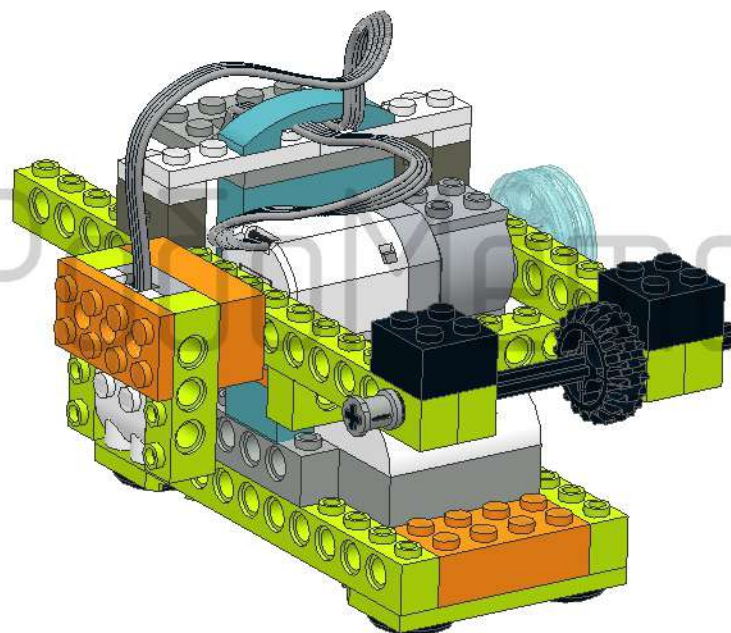
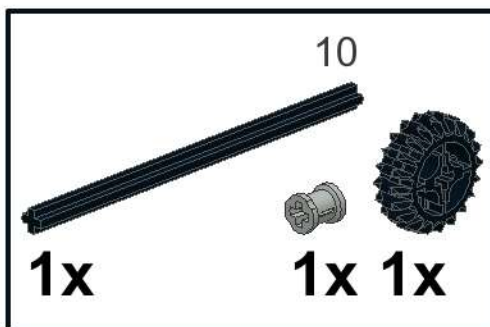
РодоМетод

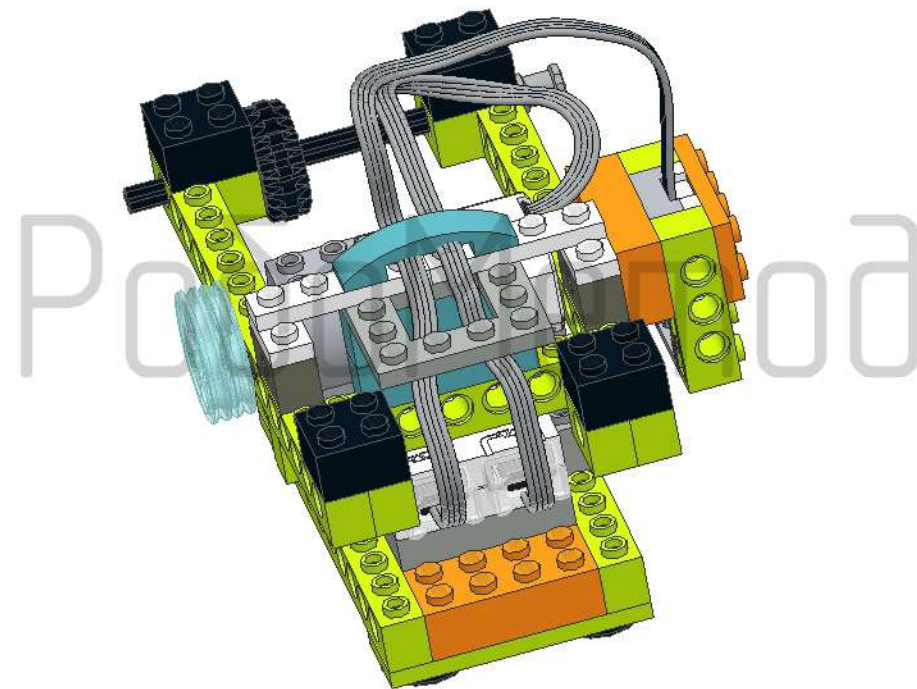


x4

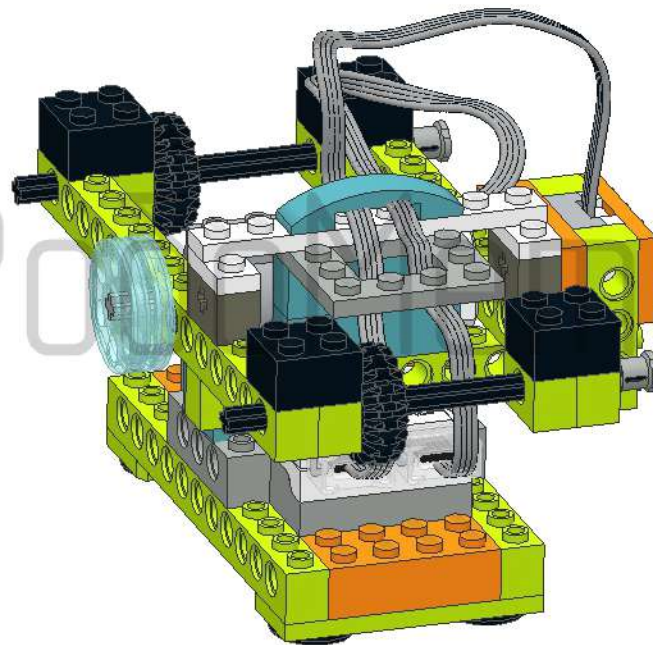
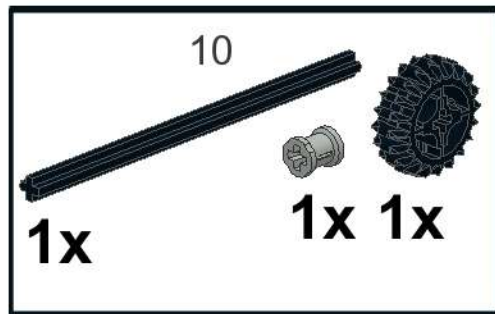


21





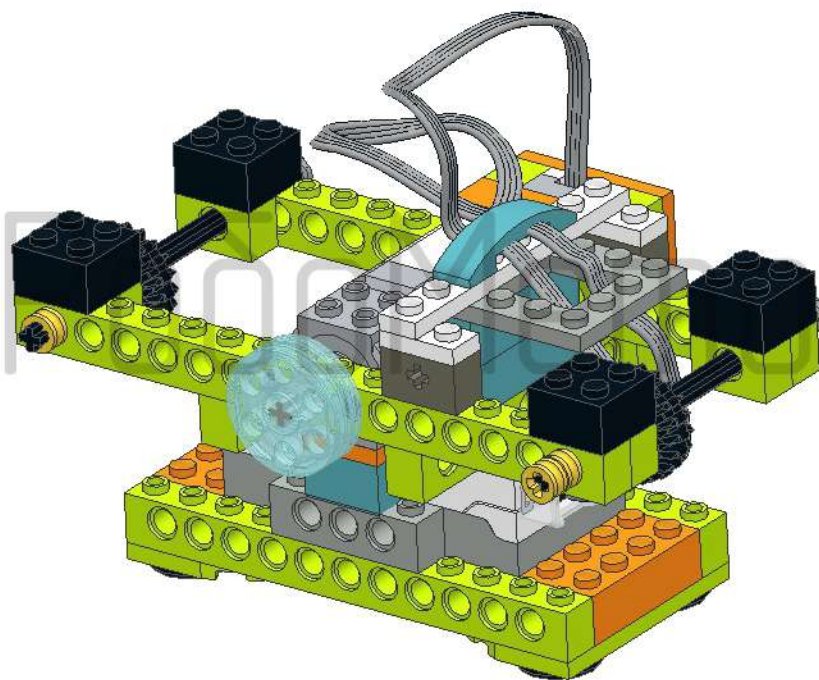
23



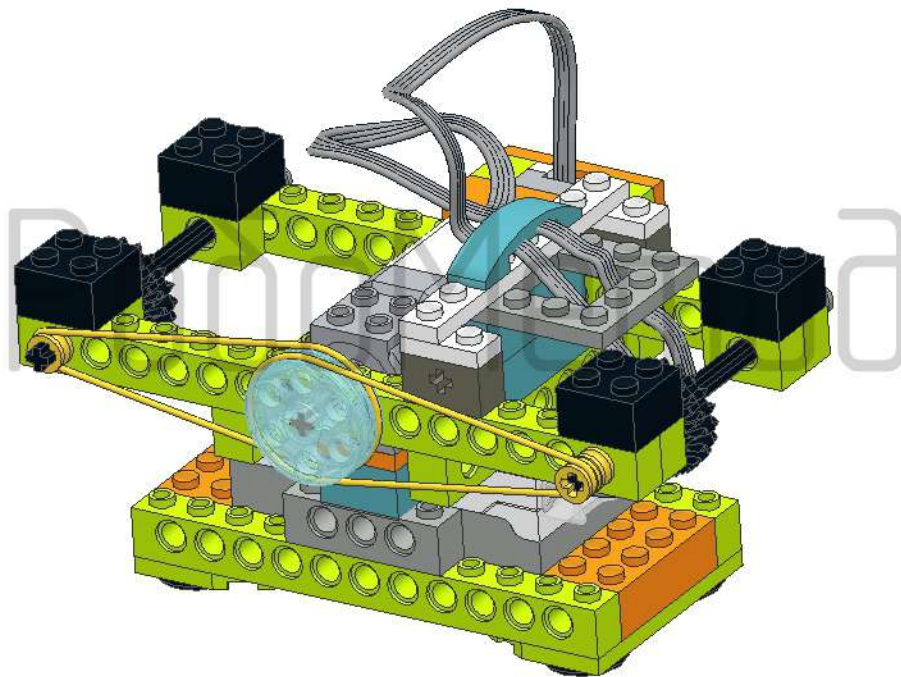
24



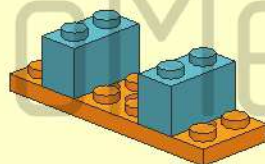
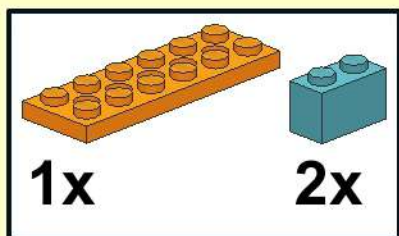
3x



25

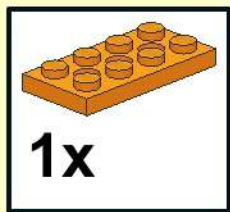


1



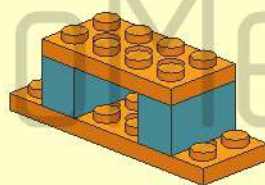
Роден Метод

2

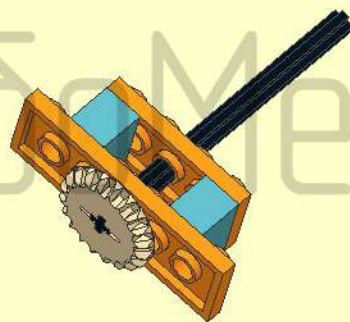
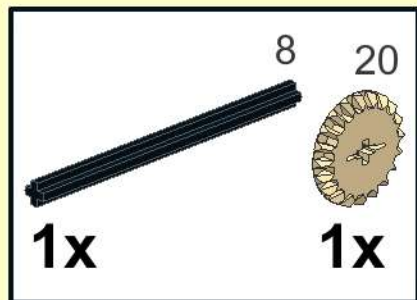


1x

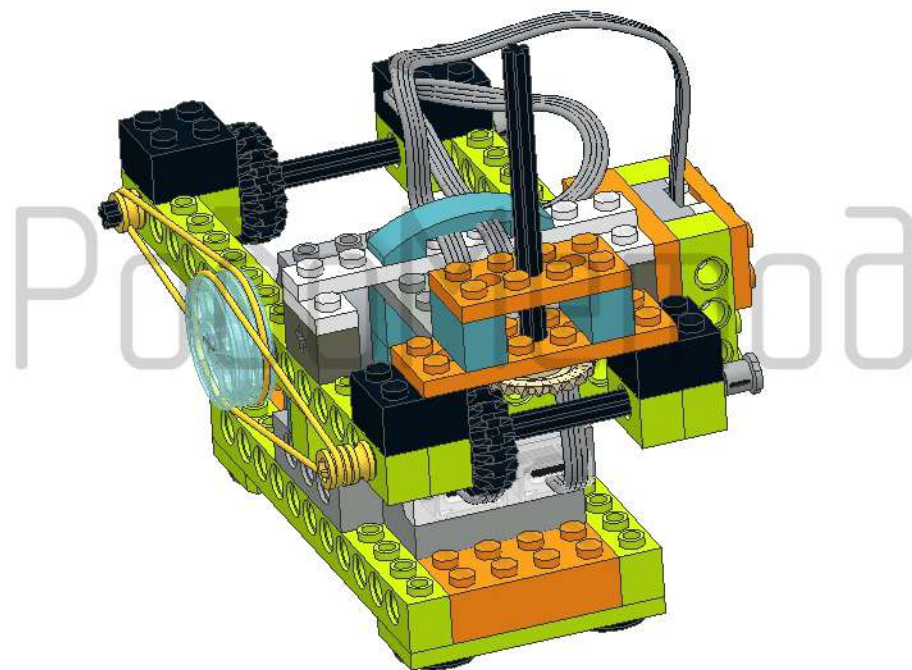
РодосМетод



3

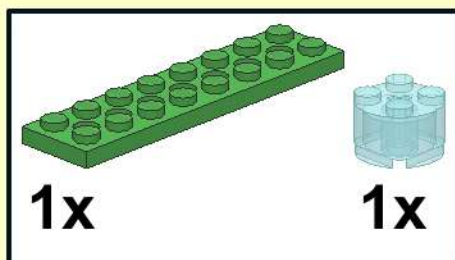


x2

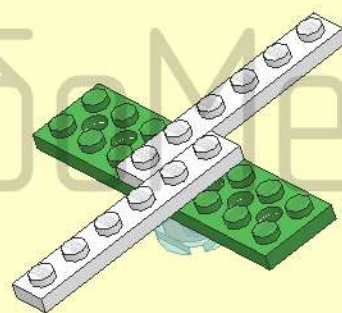
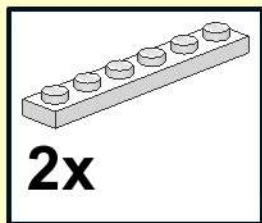




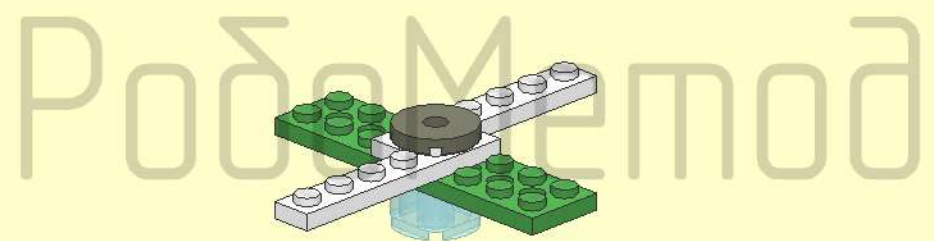
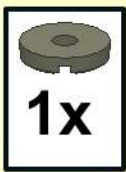
1



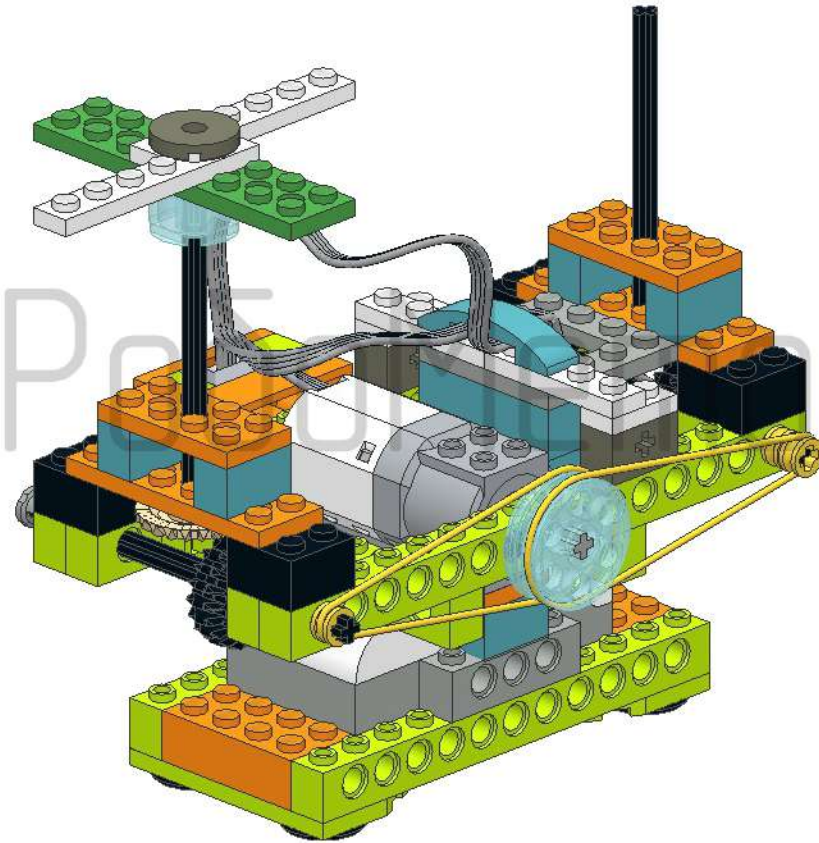
2

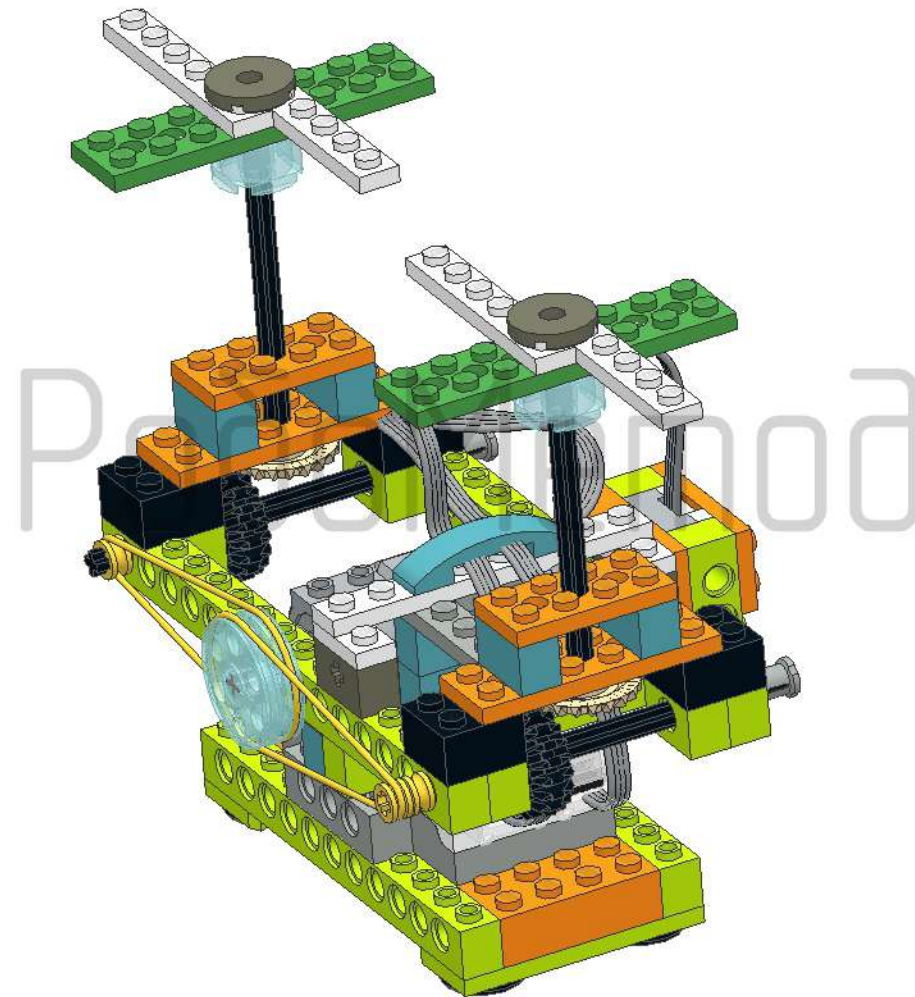


3



x2





Пример программы

При посадке мощность мотора
уменьшается.



Пример программы

Квадрокоптер стоит на земле.
Мотор заводится с громкого
звука. Сначала мощность
мотора максимальная, при
увеличении высоты – она
уменьшается.

